

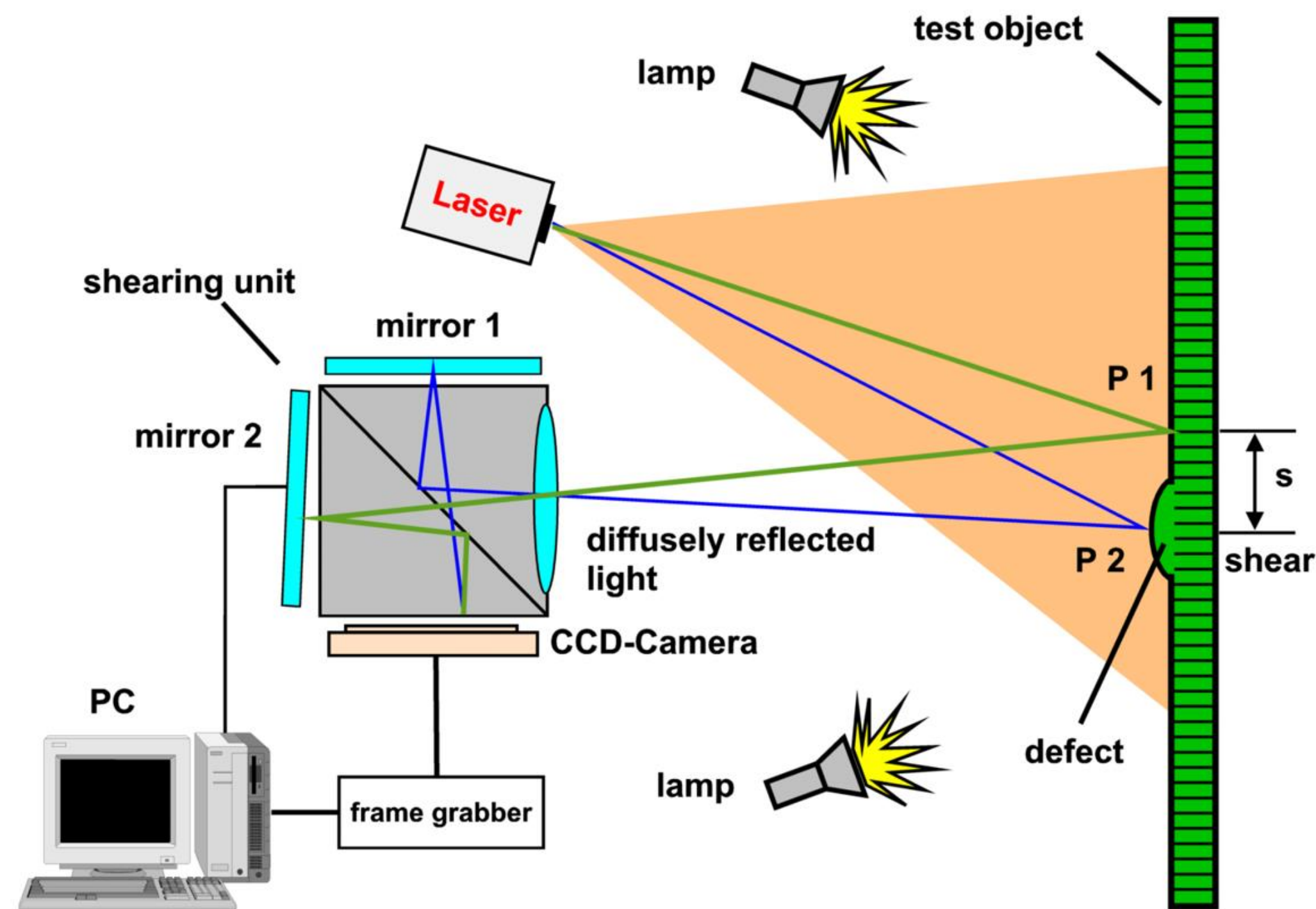


# Inspection par Shearographie

## Shearographic Testing



Principle : Inspection by shearography consists of using a heat source or another mechanical solicitation that sends a wave or vibration which penetrates an object being inspected. This wave will interact with any discontinuity present in the object which creates a surface deformation (out of place displacement). This surface displacement is detected by the shearographic camera through the projection of a laser which forms a fringe image where defect creates a discontinuity in the fringes. The image interpretation must be done by a certified level 2 ST (Shearographic Testing inspector). The inspection technique must be validated by a level 3 ST.





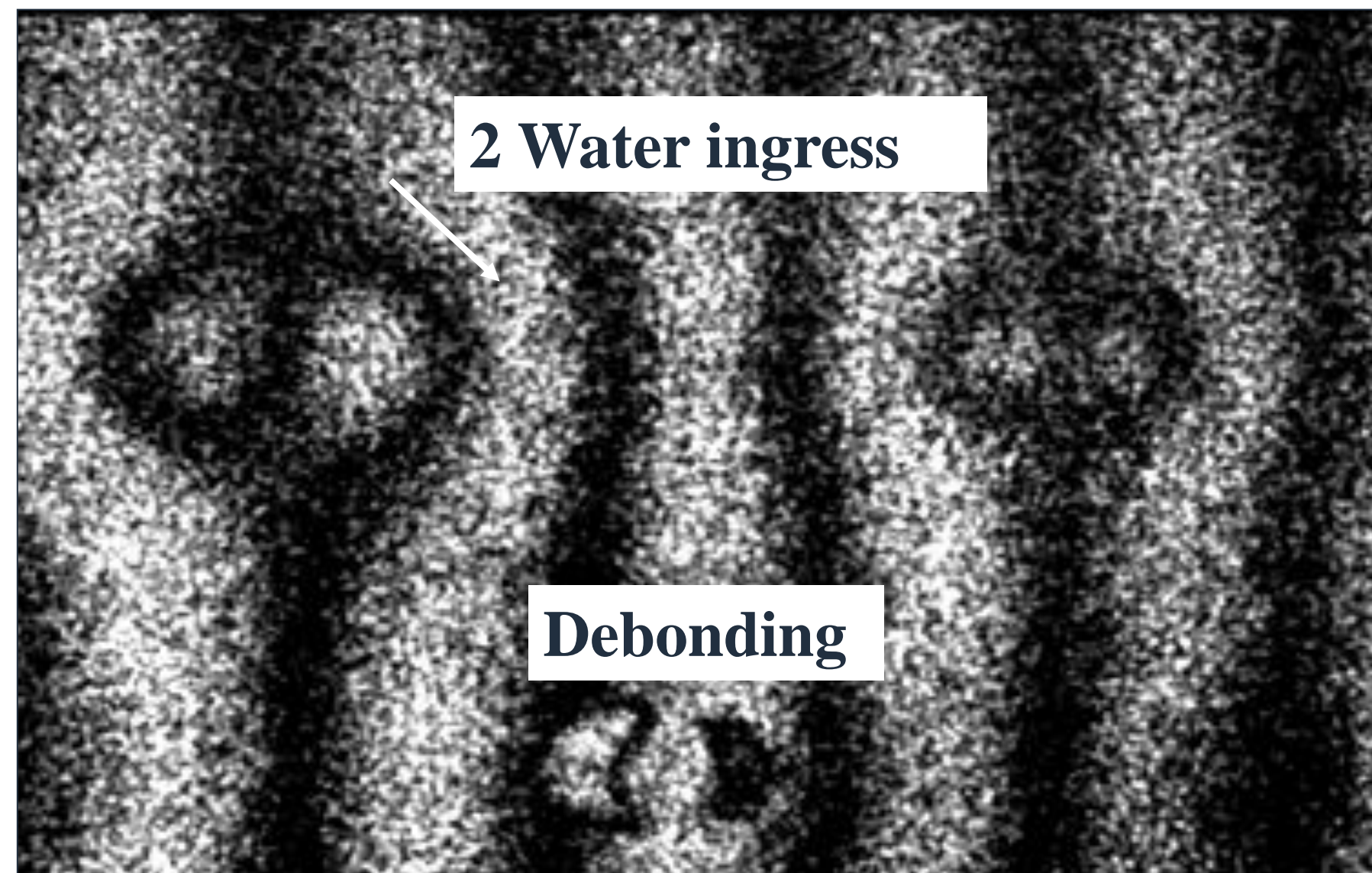
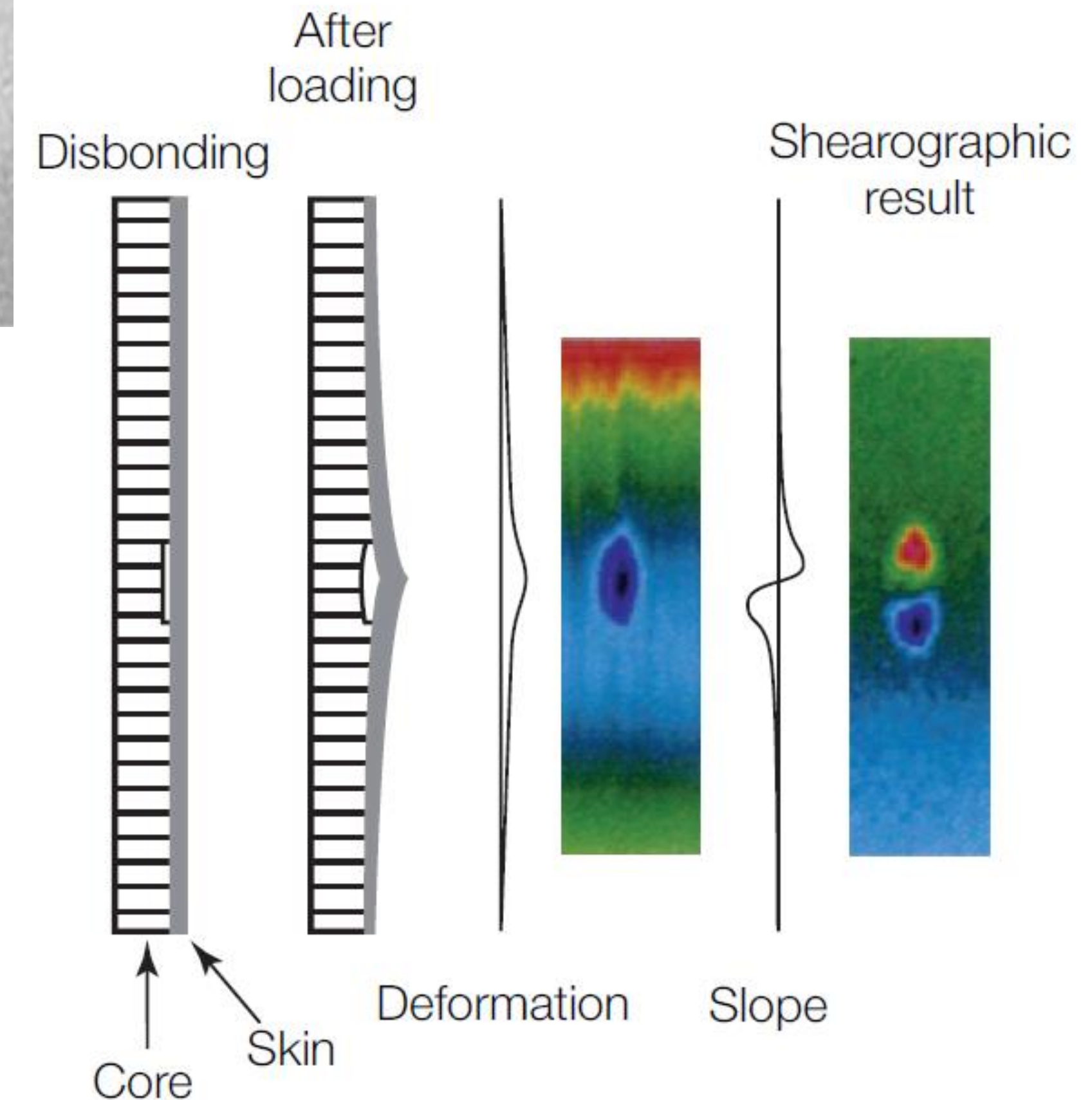
## DEFECTS SEARCHED BY SHEAROGRAPHY:

Separation zones  
Delamination  
Porosity  
disbond  
Foreign body inclusions  
Water infiltration into honeycomb

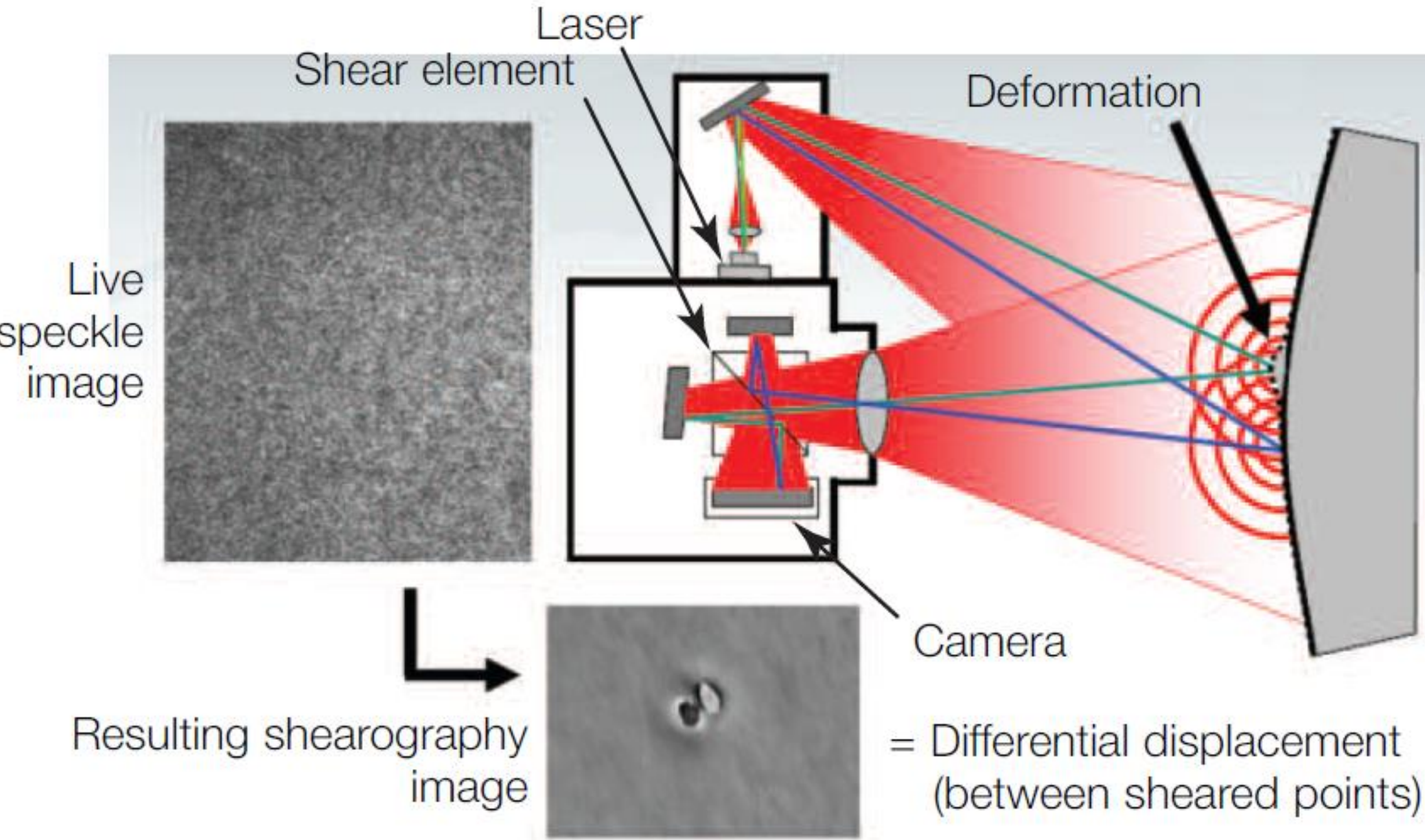
Shallow delamination in composite



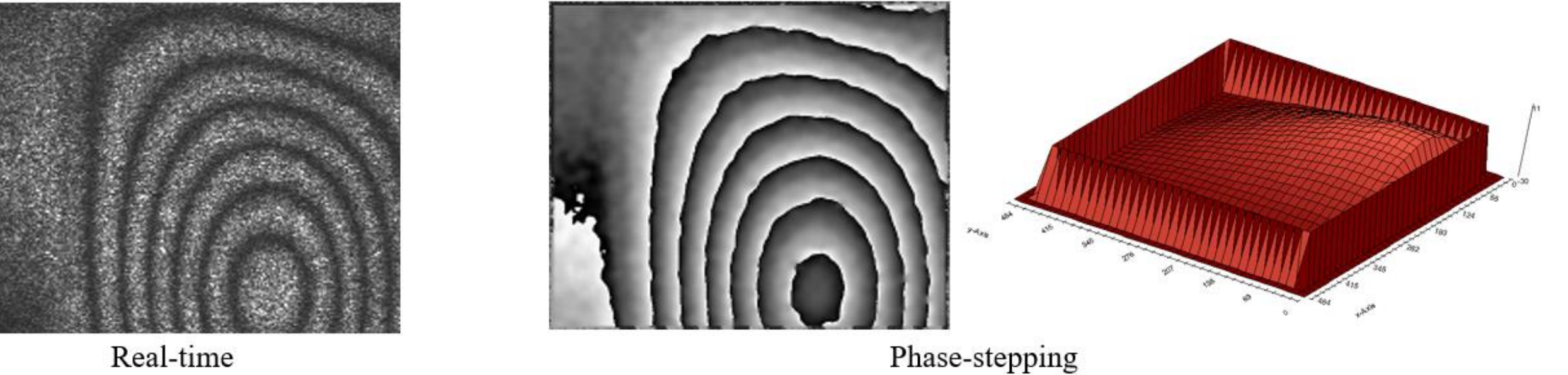
Disbond in honeycomb material







	Images	Visualization of the results		
Real-time interferometry	Intensity images	$\propto \sin \left( \frac{\Delta \varphi^{t \rightarrow t'}}{2 \pi} \right)$		Real-time
Phase-stepping interferometry	Phase images	$\Delta \varphi^{t \rightarrow t'}$		-----
	Displacement images	$\Delta d^{t \rightarrow t'}$		-----

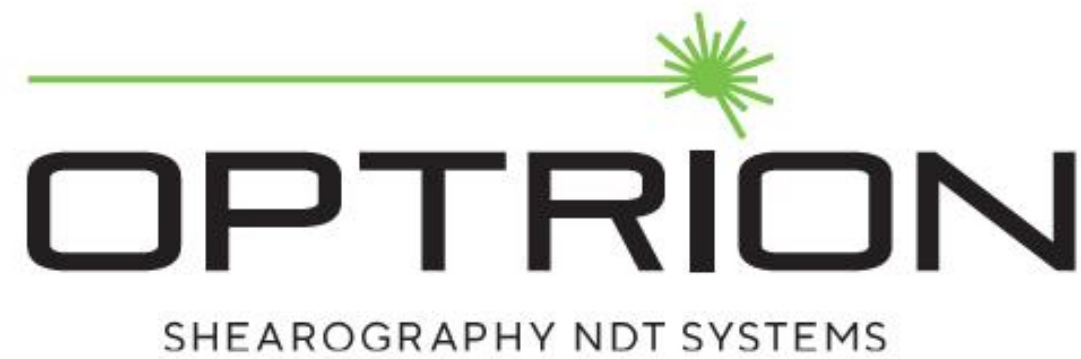


Optical Setup for Laser Shearography inspection

Different output from shearographic images



**portable** shearographic system from our partner Optrion in Belgium



Non-Destructive Testing  
for Composite Materials



## Camera Specifications

Dimensions (L x H x W): 300x150x105 mm

Weight: 5.2 kg (with IR)

Aircraft cabin compatible dimensions and weight

Light source: laser 200 mW SLM @ 532 nm (green) –  
Class 1M

CMOS Sensor: GiGE camera (H x V) 2464×2056 pixels  
– FOV 17° - 12 bit resolution

**Thermal sensor:** 640 x 480 px – 55 mK – 50 fps

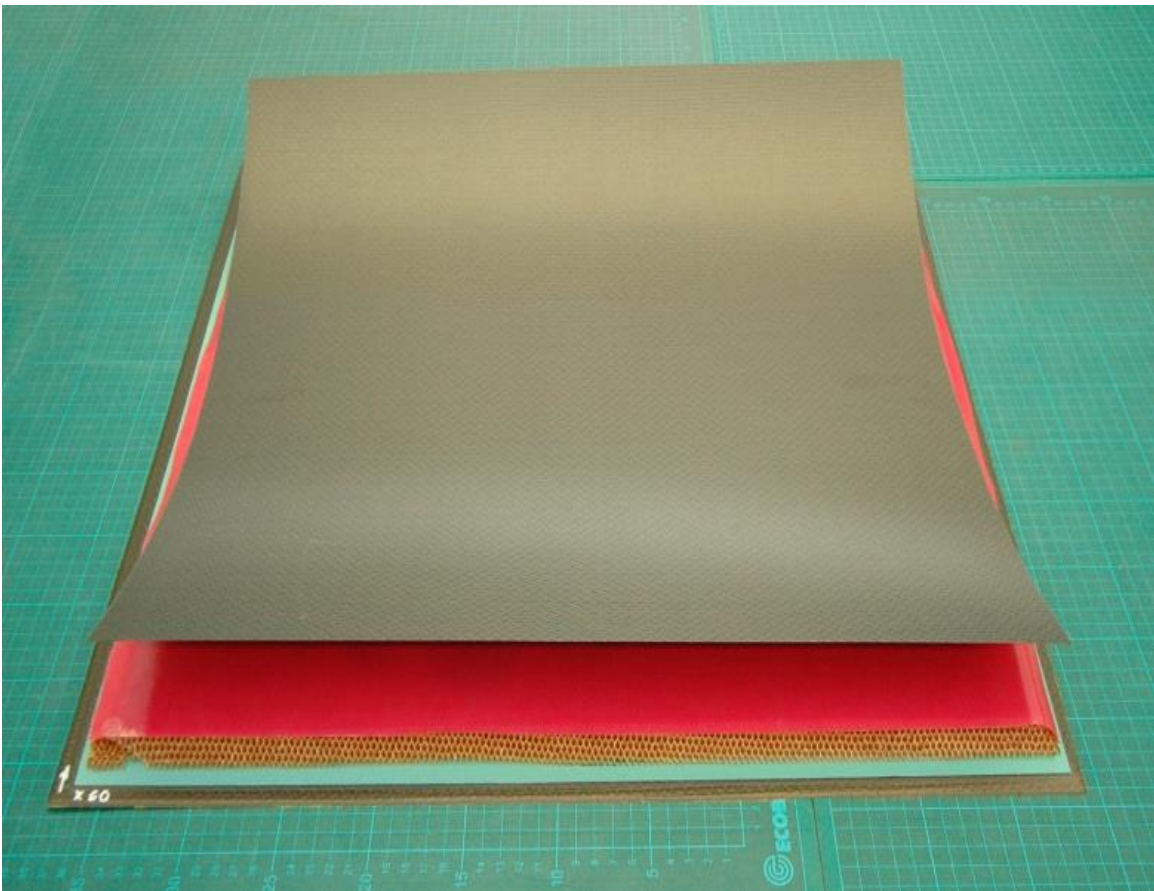
Power: 85 – 264 VAC / 50-60 Hz 60W

Laser telemeter



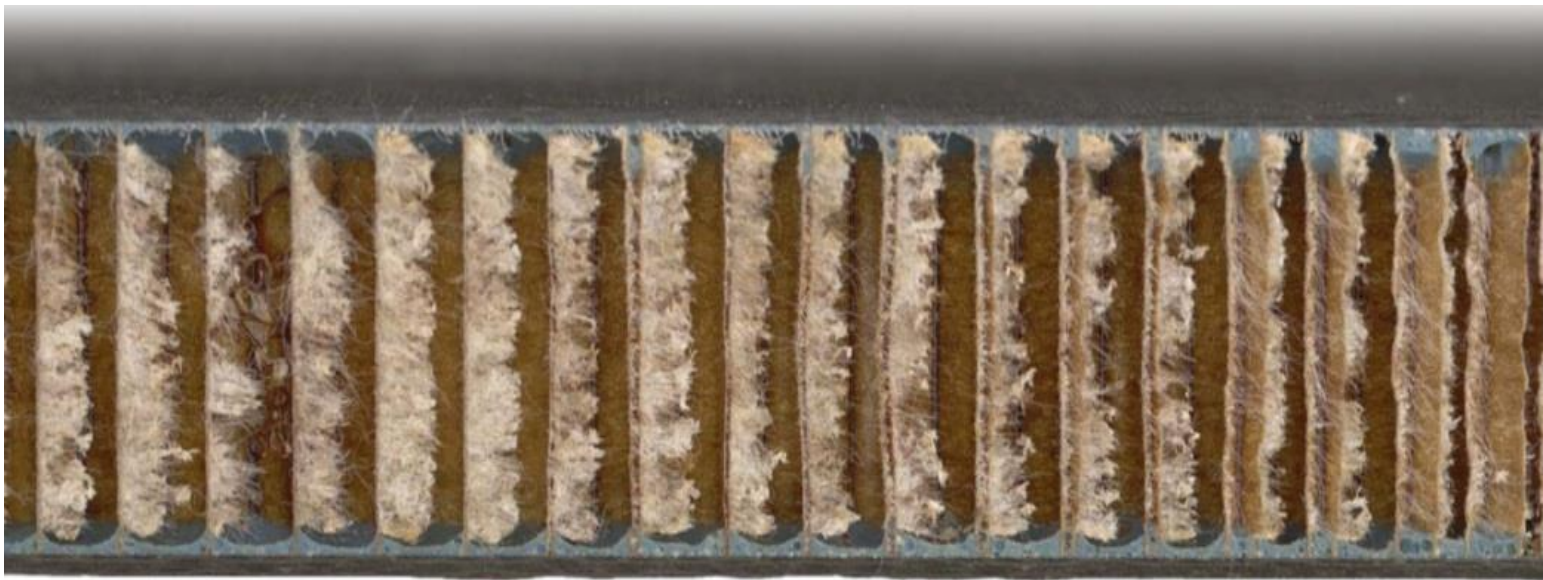
# Inspection

Part inspected



CFRP sandwich specimen; 50 x 50 cm

2 carbon skins with honeycomb

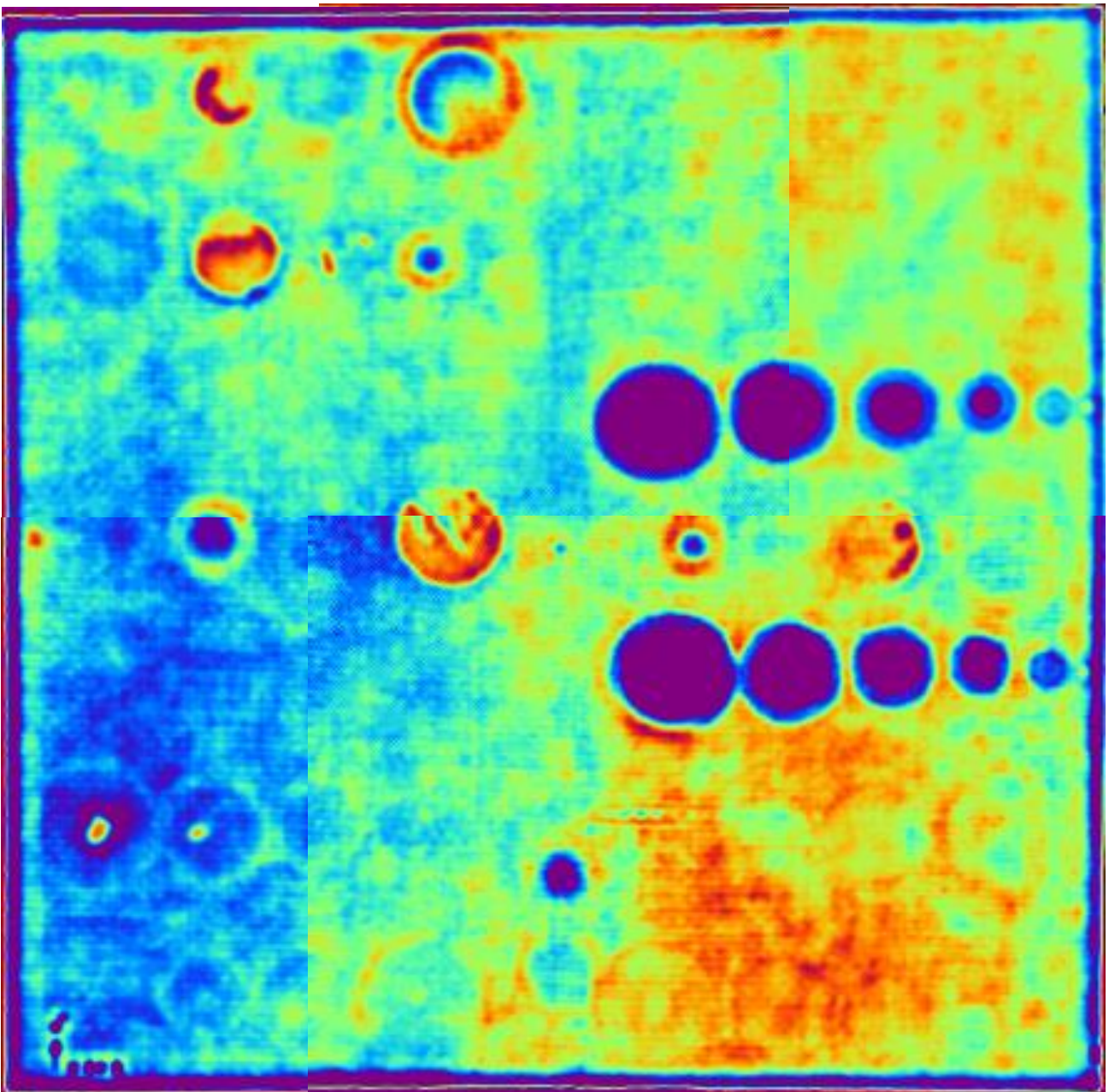
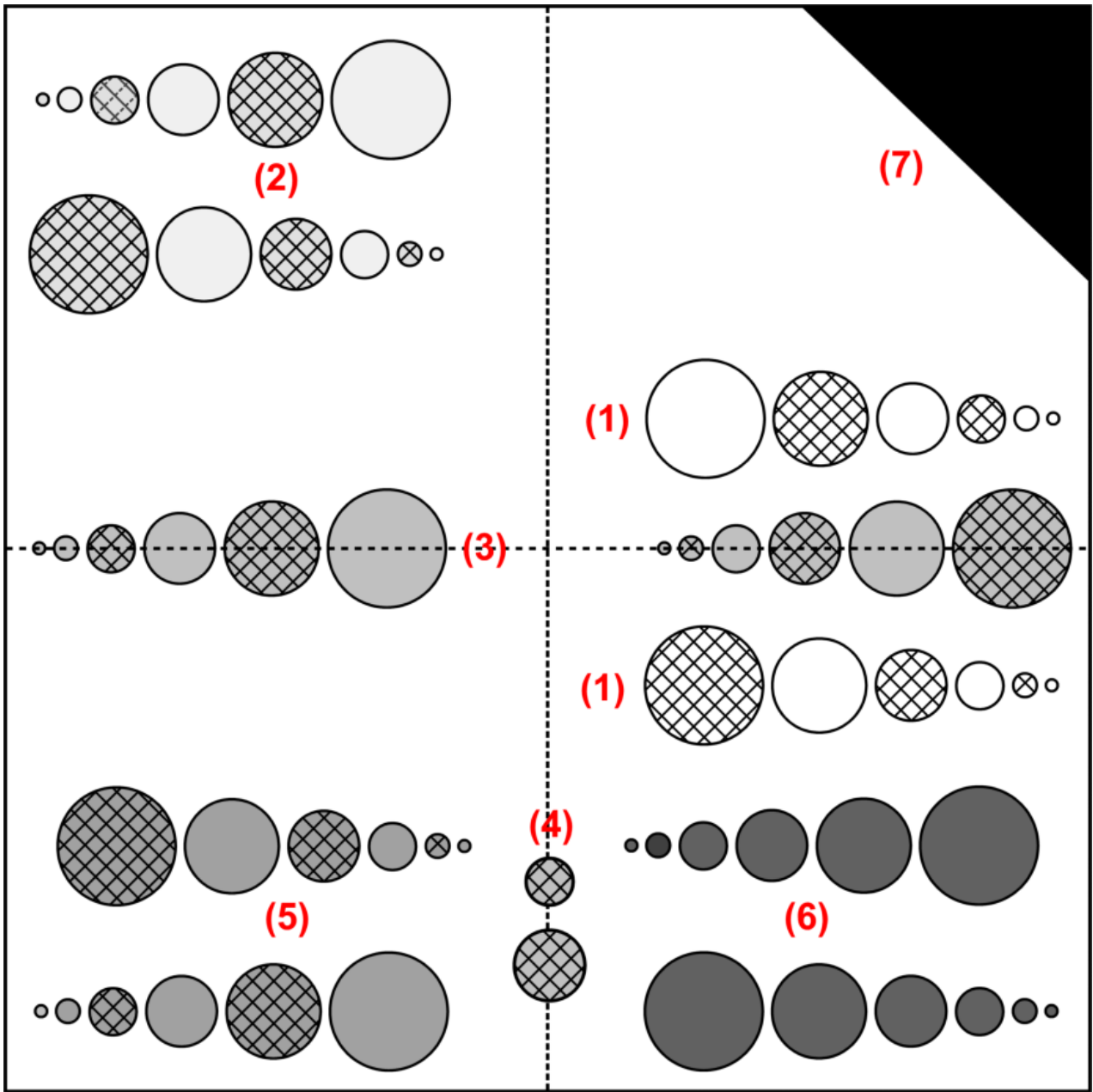


skin thickness: 1 mm  
core thickness: 16 mm

Shearographic result



4 x 1000 W Heat Pulse






Method	Equipment / Techniques	STAFF
RT Radiographic Testing	<ul style="list-style-type: none"> <li>Digital radiography (from 50KV – 320KV)</li> <li>Resolution from 50 µm – 200 µm</li> </ul>	2 RT Level 1 2 RT level 2 and 1 RT3
UT Ultrasonic Testing	<ul style="list-style-type: none"> <li>Immersion Testing</li> <li>Thickness measurement</li> <li>Phased Array Pulse Echo</li> </ul>	1 UT level 1 2 UT level 2 1 UT level 3
PT Penetrant Testing	<ul style="list-style-type: none"> <li>Red Dye or Fluorescent penetrant</li> <li>Alkaline or Solvent Degreasing</li> </ul>	4 PT level 2 1 PT level 3
MT Magnetic Particle Inspection	<ul style="list-style-type: none"> <li>Hand yokes</li> <li>Stationary MT bench</li> </ul>	3 MT level 2 1 MT level 3
IRT Infrared Thermography Testing	<ul style="list-style-type: none"> <li>Hot air heater or 4 x 1000 W Halogen heaters</li> <li>IR Camera Flir T450sc</li> </ul>	2 IRT level 2 1 IRT level 3
ST Shearographic Testing	<ul style="list-style-type: none"> <li>Hot air heater or 4 x 1000 W Halogen heaters</li> <li>Optrion Digital Shearographic Camera</li> </ul>	1 ST level 1 1 ST level 3
ET Eddy Current Testing	<ul style="list-style-type: none"> <li>High and low Frequency Eddy Current Testing</li> <li>Rotating Probe ET</li> </ul>	2 ET level 2 1 ET level 3
VT Visual Testing	<ul style="list-style-type: none"> <li>Direct VT of welds, castings and composite parts</li> <li>Indirect VT (endoscopy and digital microscope 220x)</li> </ul>	1 VT level 2 1 VT level 3

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